Lexium MDrive®

Simplifying machine building with compact integrated motors



Pulse/Direction version

Integrated stepper motors with 4 operating modes – pulse/direction, speed, torque and velocity control – and closed loop performance

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Lexium MDrive® Pulse/Direction

Modes: pulse/direction, speed, torque, velocity integrated 2-phase stepper motor





4 I/O lines

internal encoder option

closed loop performance

Product offer

Lexium MDrive® Pulse/Direction products integrate a hybrid 1.8° 2-phase stepper motor with on-board drive electronics, and closed loop performance with internal encoder option. Products operate in 4 modes: pulse/direction input, variable speed control, constant velocity drive, and variable torque control in closed loop products only. Operating in pulse/direction mode requires a separate motion control master.

Lexium MDrive Pulse/Direction products have an RS-422/485 serial interface. Product commissioning, parameterization and monitoring are accomplished via a user-friendly software GUI, included free as part of the Lexium MDrive Software Suite. Settings can be downloaded and stored in the product's nonvolatile memory.

Closed loop products are equipped with 1000 line (4000 count/rev) encoders internal to the unit, requiring no extra space in an application. Using the encoder to monitor motor shaft position, real time closed loop feedback is accomplished with hMTechnology.

Unlike traditional motor systems, hMT combines the best of servo and stepper motor technologies, while delivering unique capabilities and enhancements over both, including:

- real time closed loop control
- no loss of synchronization/stalling
- full use of motor torque
- torque mode control

Application areas

Lexium MDrive Pulse/Direction products are ideal for machine builders who want a robust motor with integrated electronics. Reduced sysem cabling can minimize problems due to electrical noise. While closed loop products deliver enhanced performance and provide a lower cost option to servo motors in many applications.

Lexium MDrive products are compact motion control solutions that can reduce system cost, design and assembly time for a wide range of motion applications.

Features

- Integrated microstepping drive and hybrid 1.8° 2-phase NEMA stepper motor
 - Standard motors available in NEMA 17, 23 & 34 sizes
 - Optional premium high torque motors available in NEMA 23 size
 - -All motors available in 3 stack lengths: single, double and triple
- Open loop control
 - Pulse/direction input
 - Variable speed control
 - Constant velocity drive
- Closed loop control with 1000 line internal encoder and hMTechnology (optional)
 - Torque mode control
- Prevents motor stalling while delivering numerous performance advantages
- Advanced current control for exceptional performance and smoothness
- RS-422/485 serial interface
- +12 up to +70 VDC input power range
- Cost effective
- Extremely compact
- 20 microstep resolutions to 51,200 steps/rev including: Degrees, Metric, Arc Minutes
- 0 to 2.56 MHz step clock rate selectable in 0.59 Hz increments
- Graphical user interface provided for quick and easy configuration
- Extended 4 year product warranty

Specifications

Lexium MDrive® Pulse/Direction

Modes: pulse/direction, speed, torque, velocity integrated 2-phase stepper motor

			LM•P42 (NEMA17)	LM•P57 (NEMA23)	LM•P85 (NEMA34)		
Input power	Voltage		+12+48 VDC	+12+60 VDC	+12+70 VDC		
	Current maximum (1)		2.0 A	3.5 A	4.0 A		
Motor	Premium high torque motor	Option	no	yes	no		
Thermal	Operating temp	Heat sink maximum	85°C				
	non-condensing	Motor maximum	100°C				
Protection	Type	Temp warning	084°C, user selectab	ole			
		Earth grounding	via product chassis gro	und lug			
		IP rating	IP20				
Signal inputs	Number		2				
	Voltage range, isolated		+5+24 VDC sourcing or sinking				
Analog input	Number		1				
	Resolution		12 bit				
	Voltage range		0+5 VDC, 0+10 VD	0+5 VDC, 0+10 VDC, 020 mA, 420 mA			
Attention output	Current	Open collector/emitter	5.5 mA	5.5 mA			
-	Voltage	Open collector	+60 VDC				
		Open emitter	+7 VDC				
Communication	Type		RS-422/485				
	Baud rate		4.8115.2 kbps				
Motion	Microstep resolution Number of settings		20				
		Steps per revolution	200, 400, 800, 1000, 1600, 2000, 3200, 5000, 6400, 10000, 12800, 2000 25000, 25600, 40000, 50000, 51200, 36000 (0.01 deg/µstep), 21600 (1 minute/µstep), 25400 (0.001mm/µstep)				
	Open loop configuration	Operating modes	pulse/direction, speed control, velocity mode				
	Closed loop configuration, requires LMD with encoder	Operating modes	pulse/direction input, va torque mode	ariable speed control, const	ant velocity mode, variable		
	Encoder	Line count	1000 lines (4000 edges	s per rev)			
		Style	internal, magnetic				
		Ouputs	6 TTL level compatible				
	Digital filter range		50 nS12.9 μS (10 MHz38.8 kHz)				
	Clock types (step mode)		Step/direction, quadrature, step up/step down, clockwise/counterclockwise				
	Step frequency	Maximum	2.56 MHz				
		Minimum pulse width	100 ns				

⁽¹⁾ Actual power supply current will depend on voltage and load.

Setup parameters (2)							
			Overview				
Operating modes	Basic	Pulse/direction	microstep resolution, run current, hold current, hold delay, clock mode, motion, enable active, input filters				
	Advanced	Speed control	acceleration, decelaration, velocity, flags				
		Torque mode (3)	set torque speed, % maintained motor torque, torque current, filtering				
		Velocity control	acceleration, decelaration, velocity, slew, flags				
Device	Analog input settings		select range and resolution				
parameters	Communication bus settings		set baud rate, enable/disable party mode and features, check sum				
	I/O settings		clock and filter settings, attention output with selectable pre-programmed fields				
	Motion settings		select motion, analog and velocity settings as available by operating mode				
	hMT settings (3)		hMT setup/status; hMT operation				
Device ID			device information, restore settings				

⁽²⁾ Refer to the LMD Software Suite Manual for details.

An optional Communication Converter is recommended with first orders.



See User Manual for complete details: motion.schneider-electric.com/manuals.htm

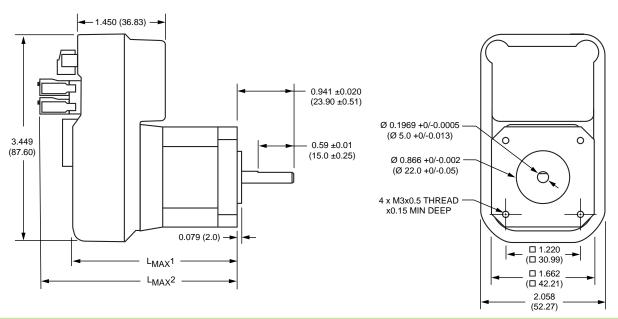
⁽³⁾ Only with Lexium MDrive closed loop/encoder products.

Lexium MDrive® Pulse/Direction

Modes: pulse/direction, speed, torque, velocity integrated 2-phase stepper motor

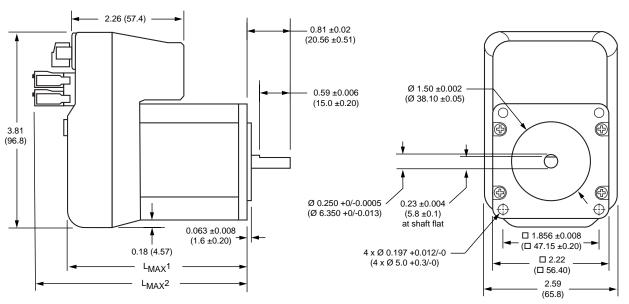
Dimensions in inches (mm)

LM•42 NEMA17 motor



Motor stack length	Lmax1	Lmax2
Single	2.40 (61.0)	3.22 (81.8)
Double	2.64 (67.0)	3.46 (88.0)
Triple	2.96 (75.3)	3.78 (96.0)

LM•57 NEMA23 motor



Motor stack length	Lmax1		Lmax2		
	Standard Motor	High Torque Motor	Standard Motor	High Torque Motor	
Single	3.17 (80.5)	3.32 (84.3)	3.91 (99.3)	4.01 (101.8)	
Double	3.52 (89.4)	3.73 (94.8)	4.26 (108.2)	4.36 (110.7)	
Triple	4.38 (111.3)	4.60 (116.8)	5.13 (130.3)	5.23 (133.0)	

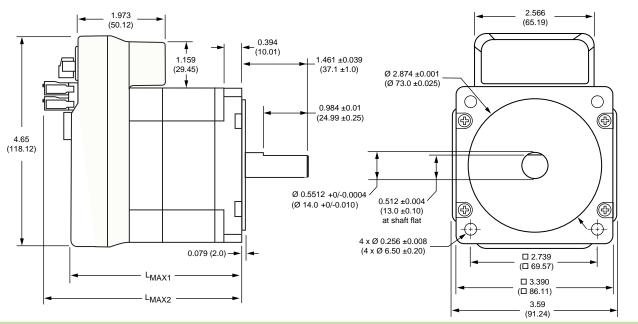
Dimensions

Lexium MDrive® Pulse/Direction

Modes: pulse/direction, speed, torque, velocity integrated 2-phase stepper motor

Dimensions in inches (mm)

LM•85 NEMA34 motor



Motor stack length	Lmax1	Lmax2
Single	3.76 (95.5)	4.41 (112.0)
Double	4.33 (110.0)	4.98 (126.5)
Triple	5.90 (149.9)	6.55 (166.4)



See User Manual for complete details: motion.schneider-electric.com/manuals.html

Connectivity and signal indicators

Lexium MDrive® Pulse/Direction

Modes: pulse/direction, speed, torque, velocity integrated 2-phase stepper motor

Software interface

The free Lexium MDrive Software Suite includes a user interface GUI for product commissioning and programming via a PC.

PC interface is easily accomplished using the USB to RS-422/485 communication converter MD-CC404-000. Compatible with 32- and 64-bit Windows, Mac OS, and Linux operating systems. Each comm converter includes a 6.0'/1.8m cable with DB9 mating connectors.

Connectors

All Lexium MDrive connectors are conveniently grouped in the same location at the back of each product. The same style locking connectors are also used consistently on all motor sizes of Lexium MDrive products.

Mating connectors for P1 and P2 are provided, and extra connectors may be ordered. A #6-32 screw lug is provided for earth grounding.

Connector	Style	Assignment
P1	2-pin screw lock	Supply voltage
P2	2 keyed 7-pin spring lock, color coded for ease of use	Multifunction interface
P3	DB9 male	Communication
Chassis ground	#6-32 screw lug	Earth grounding

Status indicators

Lexium MDrive products include 2 LED signal indicators. The multi-color LEDs are programmed to indicate a range of pre-defined messages to aid users. See product user manual for details.



Part numbers

Lexium MDrive® Pulse/Direction

Modes: pulse/direction, speed, torque, velocity integrated 2-phase stepper motor



Example	L N	ח	C	D	1	2	1
Example	L 1V	טו		٠.	7	_	
Product LM = Lexium MDrive	LN	D	С	Р	4	2	
Motor D = hybrid stepper, 1.8° H = high torque stepper, 1.8° <i>(1)</i>	L M	D	С	Р	4	2	•
Control type C = Closed loop / with hMT and encoder (2) O = Open loop / no hMT or encoder	L M	D	С	P	4	2	
Communication type P = Pulse/Direction via RS-422/485 serial interface	L M	D	С	Р	4	2	•
Flange size 42 = NEMA 17 / 42mm 57 = NEMA 23 / 57mm 85 = NEMA 34 / 85mm	L M	D	С	Ρ	4	2	•
Motor length 1 = single stack 2 = double stack 3 = triple stack	L N	D	С	Р	4	2	

- (1) Premium high torque motor option only available in NEMA 23 size.
- (2) Closed loop control delivers encoder feedback and hMT enhanced motor performance..



Installation accessories			
Description	Length m	Length feet	Reference
Communication converter, USB to RS			
USB-pluggable converter to set/program communication parameters in 32- or 64-bit. Includes pre-wired DB9 mating cable.			
■ For all RS-422/485 products	1.8	6.0	MD-CC404-000

Description	Quantity	Reference
Mating connector kit		
Mating connectors for power and multifunction interface are included with each new product. If additional mating connectors are needed for Lexium MDrive Pulse/Direction products, a single mating connector kit is offered which includes the following:		CK-14
■ 2-pin screw lock mate (DC voltage supply)	1 pc	
■ 7-pin locking mates (multifunction), keyed	2 pcs - 1 yellow , 1 gray	

Lexium MDrive® Motor specifications

LM•42 NEMA 17 motor specifications							
Motor	Stack length	Single	Double	Triple			
Holding torque	oz-in	43.9	58.1	87.8			
riolaling torque	N-cm	31	41	62			
Detent torque	oz-in	1.7	2.1	3.5			
Detent torque	N-cm	1.2	1.5	2.5			
Rotor inertia	oz-in-sec²	0.0005	0.0008	0.0012			
Rotor mertia	kg-cm ²	0.038	0.057	0.082			
Radial load limit,	lbs	8.5	8.5	8.5			
center of shaft	kg	3.8	3.8	3.8			
Axial load limit @ 1500 rpm	lbs	10	10	10			
(5000 full steps/sec)	kg	4.5	4.5	4.5			
Weight (motor+driver)	OZ	13.6	16.0	18.4			
weight (motor+driver)	g	385	454	522			

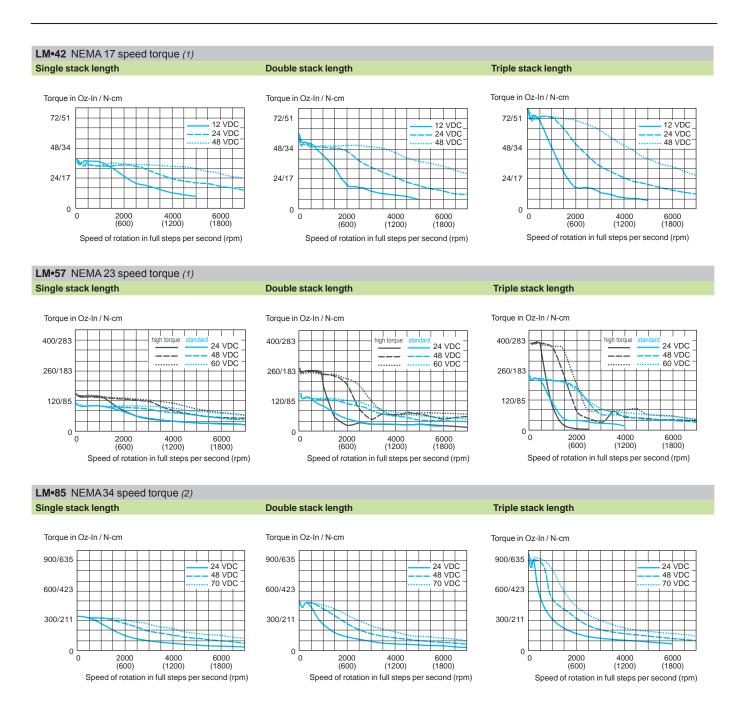
LM•57 NEMA 23 motor specifications								
Motor (1)	Stack length	Single		Double		Triple		
Motor (1)	Torque level	STD	HIGH	STD	HIGH	STD	HIGH	
Holding torque	oz-in	103.4	152.0	158.6	264.0	242.2	416.0	
Holding torque	N-cm	73.0	107.0	112.0	186.0	171.0	294.0	
Detent terrine	oz-in	3.9	8.5	5.6	14.2	9.72	21.2	
Detent torque	N-cm	2.7	6.0	3.9	10.0	6.86	15.0	
Rotor inertia	oz-in-sec ²	0.0025	0.0019	0.0037	0.0030	0.0065	0.0065	
Kotor mertia	kg-cm ²	0.18	0.14	0.26	0.22	0.46	0.46	
Radial load limit,	lbs	15	15	15	15	15	15	
center of shaft	kg	6.8	6.8	6.8	6.8	6.8	6.8	
Axial load limit @ 1500 rpm	lbs	20	20	20	20	20	20	
(5000 full steps/sec)	kg	9	9	9	9	9	9	
Weight (motor (driver)	OZ	26.4	26.4	31.2	31.2	44.0	44.0	
Weight (motor+driver)	g	748	748	885	885	1247	1247	

LM•85 NEMA 34 motor specifications							
Motor	Stack length	Single	Double	Triple			
Holding torque	oz-in	336.0	480.0	920.0			
riolaling torque	N-cm	237.0	339.0	650.0			
Detent torque	oz-in	10.9	14.16	19.83			
	N-cm	7.7	10.0	14.0			
Rotor inertia	oz-in-sec²	0.0127	0.0191	0.0382			
Kotor mertia	kg-cm ²	0.90	1.35	2.70			
Radial load limit,	lbs	65	65	65			
center of shaft	kg	29.4	29.4	29.4			
Axial load limit @ 1500 rpm	lbs	20	20	20			
(5000 full steps/sec)	kg	9	9	9			
Weight (motor (driver)	lb	4.45	5.65	9.0			
Weight (motor+driver)	kg	2.02	2.56	4.08			

⁽¹⁾ Available motors include STD/Standard and HIGH/High Torque

System performance

Lexium MDrive® Speed torque characteristics



- (1) Test conditions: 100% current, 0.84oz. damper, 0.18589 oz-in² inertia, hMT off (2) Test conditions: 100% current, 3.7oz. damper, 4.75670 oz-in² inertia, hMT off

USA SALES OFFICES

East Region

Tel. 610-573-9655

e-mail: e.region@imshome.com

Northeast Region

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e-mail: n.region@imshome.com

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e-mail: w.region@imshome.com

EUROPEAN SALES MANAGEMENT

Tel. +33/4 7256 5113 — Fax +33/4 7838 1537 e-mail: europe.sales@imshome.com

TECHNICAL SUPPORT

Tel. +00 (1) 860-295-6102 - Fax +00 (1) 860-295-6107 e-mail: etech@imshome.com

Schneider Electric Motion USA

370 N. Main Street Marlborough, CT 06447 USA

www.motion.schneider-electric.com

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